

Do waves compete or cooperate in a saturated SOA?

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1 Assumptions

Two primary cw waves injected into the SOA.

Frequency separation (detuning) ω .

Intensities such that everywhere saturation.

Equal gain for both waves, under these conditions.

Traveling wave equation for the slowly varying amplitude $E(z, t)$ of the total field :



$$E' := (\partial_z + v_g^{-1} \partial_t) E = \frac{1}{2} \{ \tilde{g}(1 - \varepsilon |E|^2) - \alpha \} E, \quad \text{b.c.: } E(0, t) = E_0 + E_1 e^{i\omega t}. \quad (1)$$

(v_g group velocity, $\tilde{g} = g - 2i\beta$ with g = gain, β = real propagation constant, ε = nonlinear gain saturation coefficient, α = optical losses).

$\omega \tau_{rek} \gg 1 \Rightarrow$ Negligible carrier population pulsations, i.e., $\tilde{g} = \text{const.}$

$$E = \sum_m f_m e^{im\omega(t-z/v_g)} \quad \text{Slowly varying partial wave amplitudes: } |f'_m| \ll \omega |f_m| \quad (2)$$

2 Conclusions

Inserting decomposition (2) into (1), averaging $\langle \dots \rangle$ over one beating period $2\pi/\omega$, restricting $\langle E^* E E \rangle$ to highest order $f_0^* f_0 f_0 + f_1^* f_0 f_1 + f_1^* f_1 f_0$ in the primary waves $m = 0, 1$:

$$f'_0 = \frac{1}{2} \left\{ \tilde{g}(1 - \varepsilon \sum_m |f_m|^2) - \alpha - \tilde{g} \varepsilon |f_1|^2 \right\} f_0, \quad (3)$$

inserting $f_0 = \sqrt{P_0} e^{i\varphi_0}$, separating intensity and phase, gives for intensity

$$(\partial_z + v_g^{-1} \partial_t) \ln(P_0) = g(1 - \varepsilon \sum_m P_m) - \alpha - g \varepsilon P_1. \quad \text{primary wave intensity equation} \quad (4)$$

Interchanging indexes 0 and 1 gives the equation for P_1 . Subtracting both equations:

$$\boxed{(\partial_z + v_g^{-1} \partial_t) \ln \left(\frac{P_0}{P_1} \right) = g \varepsilon (P_0 - P_1)} \quad (5)$$

- if somewhere $P_0/P_1 > 0$, then it further increases and vice versa. The smaller partial wave is suppressed. We have competition and not cooperation of the two primary waves.

Asymptotics for $P_{min} \ll P_{max} \approx P_{sat}$:

$$\boxed{P_{min} \sim e^{-\alpha \varepsilon P_{sat} z}}.$$

P_{sat} photon density in the saturated SOA.

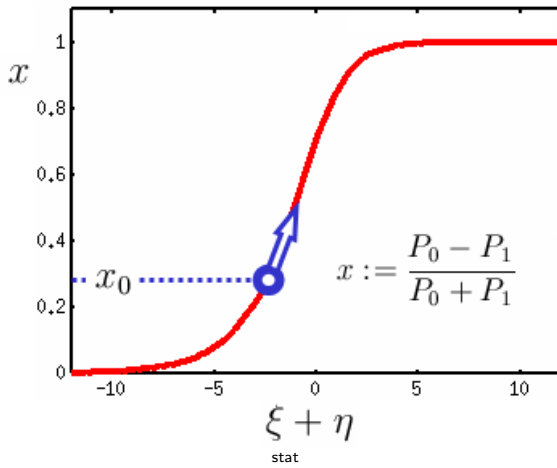
3 Stationary solution of (5)

Annahmen: $\partial_t = 0$, $P_0 + P_1 = \text{const.} = P_{sat}$, $g \approx \alpha$.

New variables

$$x := \frac{P_0 - P_1}{P_0 + P_1}, \xi = \alpha z \varepsilon P_{sat} \Rightarrow \boxed{\partial_\xi \ln\left(\frac{1+x}{1-x}\right) = x} \quad \text{universal equation} \quad (6)$$

general solution:
$$\frac{P_0 - P_1}{P_0 + P_1} = x = \frac{1}{\sqrt{1 + e^{-(\xi+\eta)}}} = \frac{x_0}{\sqrt{x_0^2 + (1 - x_0^2)e^{-\xi}}} \quad \xi = \alpha z \varepsilon P_{sat}. \quad (7)$$



This general solution is shown in the Figure. It increases monotonically with normalized coordinate ξ . The only influence of the initial power ratio parameter $x_0 = x(z = 0)$ is the starting point on this curve.

The biggest changes appear when starting at $x_0 = 0.5$, i.e. $P_0 = 3P_1$. In this case, noticeable changes should already appear along a range

$$\boxed{L_\varepsilon = \frac{1}{\varepsilon P_{sat} \alpha}} \quad (8)$$

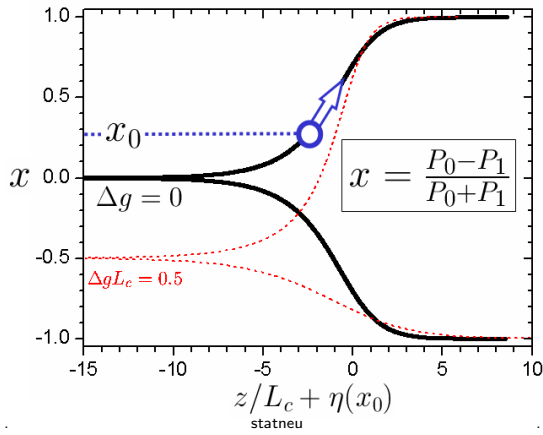
4 Stationary solution of (5) with gain difference

Up to now it was assumed that the two modes have identical gain. In praxis this can be adjusted only approximately. Therefore, I look now on the influence of a gain difference Δg between the two modes.

In this case, the only change of Equ. (5) is the additive term Δg on the right hand side. Keeping the Assumptions $\partial_t = 0$, $P_0 + P_1 = \text{const.} = P_{sat}$, $g \approx \alpha$, the solution changes to

$$\frac{z}{L_c} = \eta(x) - \eta(x_0) \quad \text{with the function} \quad \eta(x) = \frac{\ln\left(\frac{|\delta+x|}{1+x}\right)}{1-\delta} + \frac{\ln\left(\frac{|\delta+x|}{1-x}\right)}{1+\delta} \quad (9)$$

$$x = \frac{P_0 - P_1}{P_0 + P_1}, \quad \delta = \Delta g L_c, \quad L_c = \frac{1}{\alpha \varepsilon P_{sat}}.$$



This solution is shown in the Figure for $\Delta g = 0$ (thick black) and $\Delta g L_c = 0.5$. The only influence of the initial power ratio parameter $x_0 = x(z = 0)$ is the starting point on this curve. For $x_0 > -\Delta g L_c$, the solution moves up and approaches 1 for $\eta \rightarrow \infty$. Otherwise, it moves down approaching -1. In case without gain difference, this means suppression of the smaller initial power. With gain difference, the critical ratio x_0 for suppression is given by $-\Delta g L_c$.

For $\Delta g \neq 0$, the suppression becomes less pronounced in that branch in the Fig. belonging to the mode with the lower gain.

No suppression effect for $|\Delta g| L_c > 1$!!!

5 Estimate of the characteristic length L_c

First we write $L_c = \frac{1}{\alpha} \frac{P_\varepsilon}{P_{sat}}$. Here is $P_\varepsilon = \hbar \omega v_g w d / \varepsilon \approx 1 \text{ W}$ the nonlinear gain saturation power that should not be confused with the saturation power P_{sat} of the SOA. The latter one is typically 100mW, yielding the estimate $L_c \approx 10/\alpha \approx 5 \text{ mm}$ if assuming $\alpha = 20 \text{ cm}^{-1}$.

Shorter L_c require higher losses and/or lower SOA saturation power and/or lower P_ε . However, SOA saturation depends on α .

Therefore a second, different estimate. From rate equations, it can be derived (derivation will be added later)

$$L_c = \frac{1}{\alpha} + L_\varepsilon \quad \text{with} \quad L_\varepsilon = \frac{P_\varepsilon}{\hbar \omega} \frac{e}{(I - I_{tr})/L} \approx \frac{1 \text{ A/mm}}{(I - I_{tr})/L} \times 1 \text{ mm} \quad (10)$$

The first term contributes about 0.5 mm, the last one depends on how big the current can be made. With 1 A/mm we would arrive at altogether $L_c = 1.5 \text{ mm}$.

Taking more realistically 5 mm, we must have $\Delta g \ll 2 \text{ cm}^{-1}$. This is quite small.